



Introducing a New Intrinsic Metric

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Abstract. A new intrinsic metric called the t -metric is introduced. Several sharp inequalities between this metric and the most common hyperbolic type metrics are proven for various domains $G \subsetneq \mathbb{R}^n$. The behaviour of the new metric is also studied under a few examples of conformal and quasiconformal mappings, and the differences between the balls drawn with all the metrics considered are compared by both computational and analytical means.

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1. Introduction

In geometric function theory, one of the topics studied deals with the variation of geometric quantities such as distances, ratios of distances, local geometry and measures of sets under different mappings. For such studies, we need an appropriate notion of distance that is compatible with the class of mappings studied. In classical function theory of the complex plane, one of the key concepts is the *intrinsic distance*, which measures not only how close the points of the domain are to each other but also how they are located inside the domain with respect to its boundary.

The best-known example of a metric used to study intrinsic distances is the *hyperbolic metric*, which is also the foundation of the classical hyperbolic geometry. It has several desirable analytical properties but is often very difficult to define in subdomains G of an arbitrary metric space X . Because of this issue, several other newer, more general versions of the hyperbolic metric have been introduced. These generalizations share some but not all intricate features of

the hyperbolic metric and, in particular, they take into account the location of the points inside the domain. Furthermore, the closures of the balls defined with most of these metrics never intersect the boundary of the domain.

In our research, we call such a generalization of the hyperbolic metric that fulfills all the properties listed in [7, p. 79] a *hyperbolic type metric* and any metric whose values are affected by the boundary of the domain an *intrinsic metric*, regardless whether it has also the other properties of a hyperbolic type metric or not. Note that these terms might have slightly different meanings in the literature. More potential properties for a hyperbolic type metric are presented in [7, p. 191–192]. Examples of a hyperbolic type metric include the triangular ratio metric studied in [12–14], the Barrlund metric [4] and the Cassinian metric [10], whereas this work focuses on the following new intrinsic metric.

Definition 1.1. Let G be some non-empty, open, proper and connected subset of a metric space X . Choose some metric η_G defined in the closure of G and denote $\eta_G(x) = \eta_G(x, \partial G) = \inf\{\eta_G(x, z) \mid z \in \partial G\}$ for all $x \in G$. The *t-metric* for a metric η_G in a domain G is a function $t_G : G \times G \rightarrow [0, 1]$,

$$t_G(x, y) = \frac{\eta_G(x, y)}{\eta_G(x, y) + \eta_G(x) + \eta_G(y)},$$

for all $x, y \in G$.

Here, we mostly concentrate on the special case where $G \subsetneq \mathbb{R}^n$ and η_G is the Euclidean distance.

Unlike the hyperbolic type metrics, the t -metric does not have the property about the closed balls not intersecting with the boundary, see Theorem 5.5. This is an interesting aspect since this metric clearly fulfills most of the others, if not all, properties of a hyperbolic type metric in [7, p. 79]. Consequently, we have found an intrinsic metric that is not a hyperbolic type metric by our definition. It is also noteworthy that the t -metric has a very simple definition so it could potentially be a great help for researching the distortion under mappings and studying this metric further could solve one old open question, see Conjecture 4.4 and Remark 4.5.

The structure of this article is as follows. In Sect. 3, we prove that the function of Definition 1.1 is really a metric and find the sharp inequalities between this metric and several hyperbolic type metrics, including also the hyperbolic metric, in different domains. In Sect. 4, we show how the t -metric behaves under certain quasiconformal mappings and find the Lipschitz constants for Möbius maps between balls and half-spaces. Finally, in Sect. 5, we draw t -metric disks and compare their certain properties to those of other metric disks.

2. Preliminaries

In this section, we will introduce the definitions of a few different metrics and metric balls that will be necessary later on but, first, let us recall the definition of a metric.

Definition 2.1. For any non-empty space G , a *metric* is a function $\eta_G : G \times G \rightarrow [0, \infty)$ that fulfills the following three conditions for all $x, y, z \in G$:

- (1) Positivity: $\eta_G(x, y) \geq 0$, and $\eta_G(x, y) = 0$ if and only if $x = y$,
- (2) Symmetry: $\eta_G(x, y) = \eta_G(y, x)$,
- (3) Triangle inequality: $\eta_G(x, y) \leq \eta_G(x, z) + \eta_G(z, y)$.

Let η_G be any metric. An open ball defined with it is $B_{\eta}(x, r) = \{y \in G \mid \eta_G(x, y) < r\}$ and the corresponding closed ball is $\overline{B}_{\eta}(x, r) = \{y \in G \mid \eta_G(x, y) \leq r\}$. Denote the surface of these balls by $S_{\eta}(x, r)$. For Euclidean metric, these notations are $B^n(x, r)$, $\overline{B}^n(x, r)$ and $S^{n-1}(x, r)$, respectively, where n is the dimension. In this paper, the unit ball $\mathbb{B}^n = B^n(0, 1)$, the upper half-plane $\mathbb{H}^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_n > 0\}$ and the open sector $S_{\theta} = \{x \in \mathbb{C} \setminus \{0\} \mid 0 < \arg(x) < \theta\}$ with an angle $\theta \in (0, 2\pi)$ will be commonly used as domains G . Note also that the unit basis vectors of \mathbb{R}^n will be denoted by $\{e_1, \dots, e_n\}$.

Let us now define the metrics needed for a domain $G \subsetneq \mathbb{R}^n$. Denote the Euclidean distance between the points x, y by $|x - y|$ and let $d_G(x) = \inf\{|x - z| \mid z \in \partial G\}$. Suppose that the t -metric is defined with the Euclidean distance so that

$$t_G(x, y) = \frac{|x - y|}{|x - y| + d_G(x) + d_G(y)}$$

for all $x, y \in G$, if not otherwise specified.

The following hyperbolic type metrics will be considered: The triangular ratio metric: $s_G : G \times G \rightarrow [0, 1]$,

$$s_G(x, y) = \frac{|x - y|}{\inf_{z \in \partial G} (|x - z| + |z - y|)},$$

the j_G^* -metric: $j_G^* : G \times G \rightarrow [0, 1]$,

$$j_G^*(x, y) = \frac{|x - y|}{|x - y| + 2 \min\{d_G(x), d_G(y)\}},$$

and the point pair function: $p_G : G \times G \rightarrow [0, 1]$,

$$p_G(x, y) = \frac{|x - y|}{\sqrt{|x - y|^2 + 4d_G(x)d_G(y)}}.$$

Out of these hyperbolic type metrics, the triangular ratio metric was studied by Hästö [9], and the two other metrics are more recent. As pointed out in [8], the j_G^* -metric is derived from the *distance ratio metric* found by

Gehring and Osgood in [6]. Note that there are proper domains G in which the point pair function is not a metric [3, Rmk 3.1 p. 689].

Use notations sh , ch and th for the hyperbolic sine, cosine and tangent, respectively. Define then the hyperbolic metric as

$$\begin{aligned} \text{ch}_{\rho_{\mathbb{H}^n}}(x, y) &= 1 + \frac{|x - y|^2}{2d_{\mathbb{H}^n}(x)d_{\mathbb{H}^n}(y)}, \quad x, y \in \mathbb{H}^n, \\ \text{sh}^2 \frac{\rho_{\mathbb{B}^n}(x, y)}{2} &= \frac{|x - y|^2}{(1 - |x|^2)(1 - |y|^2)}, \quad x, y \in \mathbb{B}^n \end{aligned}$$

in the upper half-plane \mathbb{H}^n and in the Poincaré unit ball \mathbb{B}^n [7, (4.8), p. 52 & (4.14), p. 55]. In the two-dimensional space,

$$\text{th} \frac{\rho_{\mathbb{H}^2}(x, y)}{2} = \left| \frac{x - y}{x - \bar{y}} \right|, \quad \text{th} \frac{\rho_{\mathbb{B}^2}(x, y)}{2} = \left| \frac{x - y}{1 - x\bar{y}} \right| = \frac{|x - y|}{A[x, y]},$$

where \bar{y} is the complex conjugate of y and $A[x, y] = \sqrt{|x - y|^2 + (1 - |x|^2)(1 - |y|^2)}$ is the Ahlfors bracket [7, (3.17) p. 39].

Note that the following inequalities hold for the hyperbolic type metrics.

Lemma 2.2. [8, Lemma 2.3, p. 1125] *For a proper subdomain G of \mathbb{R}^n , the inequality $j_G^*(x, y) \leq p_G(x, y) \leq \sqrt{2}j_G^*(x, y)$ holds for all $x, y \in G$.*

Lemma 2.3. [8, Lemma 2.1, p. 1124 & Lemma 2.2, p. 1125] *For a proper subdomain G of \mathbb{R}^n , the inequality $j_G^*(x, y) \leq s_G(x, y) \leq 2j_G^*(x, y)$ holds for all $x, y \in G$.*

Lemma 2.4. [7, p. 460] *For all $x, y \in G \in \{\mathbb{H}^n, \mathbb{B}^n\}$,*

$$\begin{aligned} (1) \quad & \text{th} \frac{\rho_{\mathbb{H}^n}(x, y)}{4} \leq j_{\mathbb{H}^n}^*(x, y) \leq s_{\mathbb{H}^n}(x, y) \\ & = p_{\mathbb{H}^n}(x, y) = \text{th} \frac{\rho_{\mathbb{H}^n}(x, y)}{2} \leq 2\text{th} \frac{\rho_{\mathbb{H}^n}(x, y)}{4}, \\ (2) \quad & \text{th} \frac{\rho_{\mathbb{B}^n}(x, y)}{4} \leq j_{\mathbb{B}^n}^*(x, y) \leq s_{\mathbb{B}^n}(x, y) \leq p_{\mathbb{B}^n}(x, y) \\ & \leq \text{th} \frac{\rho_{\mathbb{B}^n}(x, y)}{2} \leq 2\text{th} \frac{\rho_{\mathbb{B}^n}(x, y)}{4}. \end{aligned}$$

3. t-Metric and Its Bounds

Now, we will prove that the function t is truly a metric in the general case.

Theorem 3.1. *For any metric space X , a domain $G \subsetneq X$ and a metric η_G defined in G , the function t_G is a metric.*

Proof. The function t_G is a metric if it fulfills all the three conditions of Definition 2.1. Trivially, the first two conditions hold. For all $k > 0$ and $x, y \geq 0$,

$$x \leq y \quad \Leftrightarrow \quad \frac{x}{x + k} \leq \frac{y}{y + k}$$

and it follows from this and the triangle inequality that

$$\begin{aligned} t_G(x, y) &= \frac{\eta_G(x, y)}{\eta_G(x, y) + \eta_G(x) + \eta_G(y)} \leq \frac{\eta_G(x, z) + \eta_G(z, y)}{\eta_G(x, z) + \eta_G(z, y) + \eta_G(x) + \eta_G(y)} \\ &\leq \frac{\eta_G(x, z)}{\eta_G(x, z) + \eta_G(x) + \eta_G(z)} + \frac{\eta_G(z, y)}{\eta_G(z, y) + \eta_G(y) + \eta_G(z)} \\ &= t_G(x, z) + t_G(z, y) \end{aligned}$$

for all $x, y, z \in G$. Thus, t_G fulfills the triangle inequality, too. □

We now show that the method of proof of Theorem 3.1 can be used to prove that several other functions are metrics.

Theorem 3.2. *If G is a proper subset of a metric space X , η_G some metric defined in the closure of G and $c_G : G \times G \rightarrow [0, \infty)$ some symmetric function such that, for all $x, y, z \in G$,*

$$c_G(x, z) \leq \eta_G(z, y) + c_G(x, y), \tag{3.3}$$

then any function $\phi_G : G \times G \rightarrow [0, 1]$, defined as

$$\phi_G(x, x) = 0, \quad \phi_G(x, y) = \frac{\eta_G(x, y)}{\eta_G(x, y) + c_G(x, y)} \text{ if } x \neq y$$

for all $x, y \in G$, is a metric in the domain G .

Proof. Since η_G is a metric and c_G is both symmetric and non-negative, the function ϕ_G trivially fulfills the first two conditions of Definition 2.1. Note that, by the triangle inequality of the metric η_G and the inequality (3.3), the inequalities

$$\begin{aligned} \eta_G(x, y) &\leq \eta_G(x, z) + \eta_G(z, y), \\ c_G(x, z) &\leq \eta_G(z, y) + c_G(x, y), \\ c_G(z, y) &\leq \eta_G(x, z) + c_G(x, y), \end{aligned}$$

hold for all $x, y, z \in G$. Now,

$$\begin{aligned} \phi_G(x, y) &= \frac{\eta_G(x, y)}{\eta_G(x, y) + c_G(x, y)} \leq \frac{\eta_G(x, z) + \eta_G(z, y)}{\eta_G(x, z) + \eta_G(z, y) + c_G(x, y)} \\ &\leq \frac{\eta_G(x, z)}{\eta_G(x, z) + c_G(x, z)} + \frac{\eta_G(z, y)}{\eta_G(z, y) + c_G(z, y)} = \phi_G(x, z) + \phi_G(z, y), \end{aligned}$$

so the function ϕ_G fulfills the triangle inequality and it must be a metric. □

Remark 3.4. (1) If the function c_G of Theorem 3.2 is strictly positive, the condition $\phi_G(x, x) = 0$ does not need to be separately specified. Namely, this condition follows directly from the fact that $\eta_G(x, x) = 0$ for a metric η_G . Note also that if c_G is a null function, the function ϕ_G becomes the discrete metric.

- (2) If η_G is a metric, then η_G^α is a metric, too, for $0 < \alpha \leq 1$, but this is not true for $\alpha > 1$ [7, Ex. 5.24, p. 80].

Corollary 3.5. *The function $\psi : \mathbb{B}^n \times \mathbb{B}^n \rightarrow [0, 1]$, defined as*

$$\psi(x, x) = 0, \quad \psi(x, y) = \frac{|x - y|}{|x - y| + c|x||y|} \text{ if } x \neq y,$$

for all $x, y \in \mathbb{B}^n$ with a constant $0 < c \leq 1$, is a metric on the unit ball.

Proof. Since now

$$c|x|(|z| - |y|) \leq ||z| - |y|| \leq |z - y| \quad \Rightarrow \quad c|x||z| \leq |z - y| + c|x||y|,$$

for all $x, y, z \in \mathbb{B}^n$, the result follows from Theorem 3.2. □

Corollary 3.6. *If G is a proper subset of a metric space X and η_G is some metric defined in the closure of G such that $\eta_G(x) = \inf\{\eta_G(x, u) \mid u \in \partial G\} \leq 1$ for all $x \in G$, then a function $v_G : G \times G \rightarrow [0, 1]$, defined as*

$$v_G(x, y) = \frac{\eta_G(x, y)}{\eta_G(x, y) + c\sqrt{(1 + \eta_G(x))(1 + \eta_G(y))}}$$

with a constant $0 < c \leq \sqrt{2}$ is a metric in the domain G .

Proof. Fix $c_G(x, y) = c\sqrt{(1 + \eta_G(x))(1 + \eta_G(y))}$. Now,

$$\begin{aligned} c_G(x, z) - c_G(x, y) &= c\sqrt{(1 + \eta_G(x))(1 + \eta_G(z))} - c\sqrt{(1 + \eta_G(x))(1 + \eta_G(y))} \\ &= c \cdot \frac{(1 + \eta_G(x))(1 + \eta_G(z)) - (1 + \eta_G(x))(1 + \eta_G(y))}{\sqrt{(1 + \eta_G(x))(1 + \eta_G(z))} + \sqrt{(1 + \eta_G(x))(1 + \eta_G(y))}} \\ &= \frac{c\sqrt{1 + \eta_G(x)}(\eta_G(z) - \eta_G(y))}{\sqrt{1 + \eta_G(z)} + \sqrt{1 + \eta_G(y)}} \leq \frac{\sqrt{2}c(\eta_G(z) - \eta_G(y))}{1 + 1} \\ &\leq \eta_G(z) - \eta_G(y) \leq \eta_G(z, y), \end{aligned}$$

so the inequality (3.3) holds for all $x, y, z \in G$ and the result follows from Theorem 3.2. □

Corollary 3.7. *The function $\chi : \mathbb{B}^n \times \mathbb{B}^n \rightarrow [0, 1]$, defined as*

$$\chi(x, y) = \frac{|x - y|}{|x - y| + c\sqrt{(2 - |x|)(2 - |y|)}}$$

for all $x, y \in \mathbb{B}^n$ with a constant $0 < c \leq \sqrt{2}$, is a metric on the unit ball.

Proof. Follows from Corollary 3.6. □

Let us focus again on the t -metric. Since the result of Theorem 3.1 holds for any metric η_G , the t -metric is a metric when defined by using the Euclidean metric. Below, we will consider the t -metric in this special case only. Let us next prove the inequalities between the t -metric and the three hyperbolic type metrics defined earlier.

Theorem 3.8. For all domains $G \subsetneq \mathbb{R}^n$ and all points $x, y \in G$, the following inequalities hold:

- (1) $j_G^*(x, y)/2 \leq t_G(x, y) \leq j_G^*(x, y)$,
- (2) $p_G(x, y)/2 \leq t_G(x, y) \leq p_G(x, y)$,
- (3) $s_G(x, y)/2 \leq t_G(x, y) \leq s_G(x, y)$.

Proof. (1) Trivially, $t_G(x, y) \leq j_G^*(x, y)$ and, by the triangle inequality,

$$d_G(x) + d_G(y) \leq |x - y| + 2 \min\{d_G(x), d_G(y)\},$$

from which it follows that

$$j_G^*(x, y) \leq \frac{2|x - y|}{|x - y| + 2 \min\{d_G(x), d_G(y)\} + d_G(x) + d_G(y)} \leq 2t_G(x, y).$$

(2) From Lemma 2.2 and Theorem 3.8(1), it follows that $t_G(x, y) \leq p_G(x, y)$.

Let us now prove that $p_G(x, y)/2 \leq t_G(x, y)$. This is clearly equivalent to

$$|x - y| + d_G(x) + d_G(y) \leq 2\sqrt{|x - y|^2 + 4d_G(x)d_G(y)}. \tag{3.9}$$

Fix $u = |x - y|$, $v = \min\{d_G(x), d_G(y)\}$ and $k = |d_G(x) - d_G(y)|$. The inequality (3.9) is now

$$\begin{aligned} u + 2v + k &\leq 2\sqrt{u^2 + 4v(v + k)} \\ \Leftrightarrow k^2 + 4uv + 2uk - 3u^2 - 12v^2 - 12kv &\leq 0. \end{aligned}$$

Define a function $f(k) = k^2 + 4uv + 2uk - 3u^2 - 12v^2 - 12kv$. Since the inequality above is equivalent to $f(k) \leq 0$, we need to find out the greatest value of this function. There is no upper limit for $u \geq 0$ or $v \geq 0$, but $0 \leq k \leq u$. We can solve that

$$f'(k) = 2k + 2u - 12v = 0 \quad \Leftrightarrow \quad k = 6v - u.$$

Since

$$\begin{aligned} f(0) &= -3u^2 + 4uv - 12v^2 \leq -2u^2 - 8v^2 \leq 0, \\ f(6v - u) &= -4u^2 + 16uv - 48v^2 \leq -32v^2 \leq 0, \\ f(u) &= -8uv - 12v^2 \leq 0, \end{aligned}$$

$f(k)$ is always non-positive on the closed interval $k \in [0, u]$ and, consequently, the inequality $p_G(x, y)/2 \leq t_G(x, y)$ follows.

(3) By the triangle inequality and Lemma 2.3 and Theorem 3.8(1),

$$\begin{aligned} \frac{s_G(x, y)}{2} &\leq \frac{|x - y|}{\inf_{z \in \partial G} (|x - z| + |z - y|) + d_G(x) + d_G(y)} \\ &\leq t_G(x, y) \leq j_G^*(x, y) \leq s_G(x, y). \end{aligned}$$

□

Proposition 3.10. *For any fixed domain $G \subsetneq \mathbb{R}^n$, the inequalities of Theorem 3.8 are sharp.*

Proof. For a proper subdomain G , there is some ball $B^n(x, r) \subset G$ with $S^{n-1}(x, r) \cap \partial G \neq \emptyset$ where $r > 0$. Fix $z \in S^{n-1}(x, r) \cap \partial G$ and $y \in [x, z]$ so that $|y - z| = kr$ with $k \in (0, 1)$. Clearly, $d_G(x) = r$, $d_G(y) = kr$, $|x - y| = (1 - k)r$ and $\inf_{z \in \partial G} (|x - z| + |z - y|) = (1 + k)r$. It follows that

$$\begin{aligned} \lim_{k \rightarrow 0^+} \frac{t_G(x, y)}{j_G^*(x, y)} &= \lim_{k \rightarrow 0^+} \frac{t_G(x, y)}{p_G(x, y)} = \lim_{k \rightarrow 0^+} \frac{t_G(x, y)}{s_G(x, y)} = \lim_{k \rightarrow 0^+} \left(\frac{1 + k}{2} \right) = \frac{1}{2}, \\ \lim_{k \rightarrow 1^-} \frac{t_G(x, y)}{j_G^*(x, y)} &= \lim_{k \rightarrow 1^-} \frac{t_G(x, y)}{p_G(x, y)} = \lim_{k \rightarrow 1^-} \frac{t_G(x, y)}{s_G(x, y)} = \lim_{k \rightarrow 1^-} \left(\frac{1 + k}{2} \right) = 1. \end{aligned}$$

Thus, regardless of how G is chosen, the inequalities of Theorem 3.8 are sharp. \square

Next, we will study the connection between the t -metric and the hyperbolic metric.

Lemma 3.11. *For all $x, y \in \mathbb{B}^2$, the inequality $|x - y| + 2 - |x| - |y| \leq 2A[x, y]$ holds.*

Proof. By the triangle inequality, $|x - y|^2 \geq (|x| - |y|)^2$ holds and therefore

$$A[x, y] \geq \sqrt{(|x| - |y|)^2 + (1 - |x|^2)(1 - |y|^2)} = 1 - |x||y|.$$

Thus, the inequality in the lemma holds if

$$|x - y| + 2 - |x| - |y| \leq 2(1 - |x||y|) \iff |x - y| \leq |x| + |y| - 2|x||y|.$$

Suppose then that $|x - y| > |x| + |y| - 2|x||y|$. By [1, Lemma 7.57.(1), p. 152],

$$A[x, y] \geq |x - y| + (1 - |x|)(1 - |y|)$$

for all $x, y \in \mathbb{B}^2$. Because

$$\begin{aligned} |x - y| + 2 - |x| - |y| &\leq 2|x - y| + 2(1 - |x|)(1 - |y|) \\ &\iff |x - y| \geq |x| + |y| - 2|x||y|, \end{aligned}$$

the inequality of the lemma holds in this case, too. \square

Theorem 3.12. *For all $x, y \in G \in \{\mathbb{H}^n, \mathbb{B}^n\}$, the inequality*

$$\frac{1}{2} \operatorname{th} \frac{\rho_G(x, y)}{2} \leq t_G(x, y) \leq \operatorname{th} \frac{\rho_G(x, y)}{2}$$

holds and the constants here are sharp.

Proof. If $G = \mathbb{H}^n$, the inequality follows directly from Lemma 2.4(1) and Theorem 3.8(3), and its sharpness from Proposition 3.10. By Lemma 2.4(2) and Theorem 3.8(1),

$$t_{\mathbb{B}^n}(x, y) \leq j_{\mathbb{B}^n}^*(x, y) \leq \operatorname{th} \frac{\rho_{\mathbb{B}^n}(x, y)}{2}$$

for all $x, y \in \mathbb{B}^n$ and this is sharp because $x = ke_1$ and $y = -ke_1$ fulfill $\lim_{k \rightarrow 1^-} (t_{\mathbb{B}^n}(x, y) / \text{th}(\rho_{\mathbb{B}^n}(x, y)/2)) = 1$. By Lemma 3.11,

$$\frac{t_{\mathbb{B}^2}(x, y)}{\text{th}(\rho_{\mathbb{B}^2}(x, y)/2)} = \frac{A[x, y]}{|x - y| + 2 - |x| - |y|} \geq \frac{1}{2}.$$

Since the values of the t -metric and the hyperbolic metric in the domain \mathbb{B}^n only depend on how the points x, y are located on the two-dimensional plane containing these two points and the origin, the inequality above holds also in the general case where $n \geq 2$. This inequality is sharp: For $x = ke_1$ and $y = -ke_1$, $\lim_{k \rightarrow 0^+} (t_{\mathbb{B}^n}(x, y) / \text{th}(\rho_{\mathbb{B}^n}(x, y)/2)) = 1/2$. \square

Theorem 3.13. *For a fixed angle $\theta \in (0, 2\pi)$ and for all $x, y \in S_\theta$, the following inequalities hold:*

- (1) $t_{S_\theta}(x, y) \leq \text{th}(\rho_{S_\theta}(x, y)/2) \leq 2(\pi/\theta) \sin(\theta/2)t_{S_\theta}(x, y)$ if $\theta \in (0, \pi)$,
- (2) $t_{S_\theta}(x, y) \leq \text{th}(\rho_{S_\theta}(x, y)/2) \leq 2t_{S_\theta}(x, y)$ if $\theta = \pi$,
- (3) $(\pi/\theta)t_{S_\theta}(x, y) \leq \text{th}(\rho_{S_\theta}(x, y)/2) \leq 2t_{S_\theta}(x, y)$ if $\theta \in (\pi, 2\pi)$.

Proof. Follows from Theorems 3.8(3) and 3.12, and [14, Cor. 4.9, p. 9]. \square

4. Quasiconformal Mappings and Lipschitz Constants

In this section, we will study the behaviour of the t -metric under different conformal and quasiconformal mappings in order to demonstrate how this metric works.

Remark 4.1. The t -metric is invariant under all similarity maps. In particular, the t -metric defined in a sector S_θ is invariant under a reflection over the bisector of the sector and a stretching $x \mapsto r \cdot x$ with any $r > 0$. Consequently, this allows us to make certain assumptions when choosing the points $x, y \in S_\theta$.

First, let us study how the t -metric behaves under a K -quasiconformal homeomorphism between two sectors, see [15, Ch. 2] for the definition of this type of mappings. Let $c(K)$ be as in [7, Thm 16.39, p. 313]

$$c(K) \leq v(K - 1) + K, \quad v = \log(2(1 + \sqrt{1 - 1/e^2})) < 1.3507.$$

Now, $c(K) \geq K$ and $c(K) \rightarrow 1$ whenever $K \rightarrow 1$. See also the book [5] by F.W. Gehring and K. Hag.

Theorem 4.2. *If $\alpha, \beta \in (0, 2\pi)$ and $f : S_\alpha \rightarrow S_\beta = f(S_\alpha)$ is a K -quasiconformal homeomorphism, the following inequalities hold for all $x, y \in S_\alpha$.*

- (1)
$$\frac{\beta}{2c(K)^K \pi \sin(\beta/2)} t_{S_\alpha}(x, y)^K \leq t_{S_\beta}(f(x), f(y))$$

$$\leq c(K) \left(\frac{\pi}{\alpha} \sin\left(\frac{\alpha}{2}\right)\right)^{1/K} t_{S_\alpha}(x, y)^{1/K}$$

if $\alpha, \beta \in (0, \pi]$,
- (2)
$$\frac{1}{2c(K)^K} t_{S_\alpha}(x, y)^K \leq t_{S_\beta}(f(x), f(y))$$

$$\leq \frac{c(K)\beta}{\pi} \left(\frac{\pi}{\alpha} \sin\left(\frac{\alpha}{2}\right)\right)^{1/K} t_{S_\alpha}(x, y)^{1/K}$$

if $\alpha \in (0, \pi)$ and $\beta \in (\pi, 2\pi)$,
- (3)
$$\frac{1}{2} \left(\frac{\pi}{c(K)\alpha}\right)^K t_{S_\alpha}(x, y)^K \leq t_{S_\beta}(f(x), f(y)) \leq \frac{c(K)\beta}{\pi} t_{S_\alpha}(x, y)^{1/K}$$

if $\alpha, \beta \in [\pi, 2\pi)$.

Proof. Follows from Theorem 3.8(3) and [14, Cor. 5.7, p. 12]. □

Let us now find Lipschitz constants of a few different mappings for the t -metric.

Theorem 4.3. *For all conformal mappings $f : G_1 \rightarrow G_2 = f(G_1)$ with $G_1, G_2 \in \{\mathbb{H}^n, \mathbb{B}^n\}$, the inequality*

$$\frac{1}{2} t_{G_1}(x, y) \leq t_{G_2}(f(x), f(y)) \leq 2t_{G_1}(x, y)$$

holds for all $x, y \in G_1$.

Proof. Follows from Theorem 3.12 and the conformal invariance of the hyperbolic metric. □

It follows from Theorem 4.3 that the Lipschitz constant $\text{Lip}(f|G_1)$ for the t -metric in any conformal mapping $f : G_1 \rightarrow G_2 = f(G_1)$, $G_1, G_2 \in \{\mathbb{H}^n, \mathbb{B}^n\}$, is at most 2. Suppose now that h is the Möbius transformation $h : \mathbb{B}^2 \rightarrow \mathbb{H}^2$, $h(z) = (1 - z)i/(1 + z)$. Since, for $x = 0$ and $y = \frac{1-k}{k+1}$ with $0 < k < 1$,

$$\lim_{k \rightarrow 1^-} \left(\frac{t_{\mathbb{H}^n}(h(x), h(y))}{t_{\mathbb{B}^n}(x, y)} \right) = \lim_{k \rightarrow 1^-} (k + 1) = 2,$$

the Lipschitz constant $\text{Lip}(h|\mathbb{B}^2)$ is equal to 2. However, for certain fixed choices of the Möbius transformation h , there is an even better Lipschitz constant $\text{Lip}(h|\mathbb{B}^2)$ than 2. For instance, the following conjecture is supported by several numerical tests.

Conjecture 4.4. *For all $a, x, y \in \mathbb{B}^2$, the Möbius transformation $T_a : \mathbb{B}^2 \rightarrow \mathbb{B}^2$, $T_a(z) = (z - a)/(1 - \bar{a}z)$ fulfills the inequality*

$$t_{\mathbb{B}^2}(T_a(x), T_a(y)) \leq (1 + |a|)t_{\mathbb{B}^2}(x, y).$$

Remark 4.5. It is also an open question whether the inequality of Conjecture 4.4 holds for the triangular ratio metric or so called Barrlund metric, but numerical tests suggest so, see [3, Conj. 1.6, p. 684] and [4, Conj. 4.3, p. 25].

In the next few results, we will study a mapping $f^* : S_\theta \rightarrow S_\theta$, $f^*(x) = x/|x|^2$ defined in some open sector S_θ , and find its Lipschitz constants for the t -metric.

Theorem 4.6. *If $\theta \in (0, \pi]$ and f^* is the mapping $f^* : S_\theta \rightarrow S_\theta$, $f^*(x) = x/|x|^2$, the Lipschitz constant $Lip(f^*|_{S_\theta})$ for the t -metric is $1 + \sin(\theta/2)$.*

Proof. Without loss of generality, we can fix $x = e^{hi}$ and $y = re^{ki}$ with $0 < h \leq \theta/2$, $h \leq k < \theta$ and $r > 0$. Since $x^* = e^{hi}$ and $y^* = (1/r)e^{ki}$, it follows that

$$\frac{t_{S_\theta}(x^*, y^*)}{t_{S_\theta}(x, y)} = \frac{\sqrt{1 + r^2 - 2r \cos(k - h)} + \sin(h) + r \sin(\min\{k, \theta - k\})}{\sqrt{1 + r^2 - 2r \cos(k - h)} + r \sin(h) + \sin(\min\{k, \theta - k\})}.$$

To maximize this, we clearly need to choose $k = \theta/2$ and make r and h as small as possible. If $k = \theta/2$,

$$\lim_{h \rightarrow 0^+, r \rightarrow 0^+} \frac{t_{S_\theta}(x^*, y^*)}{t_{S_\theta}(x, y)} = 1 + \sin(\theta/2),$$

so the theorem follows. □

Theorem 4.7. *If $x^* = x/|x|^2$ and $y^* = y/|y|^2$, the equality $s_{S_\theta}(x, y) = s_{S_\theta}(x^*, y^*)$ holds in an open sector S_θ with $\theta \in (0, 2\pi)$.*

Proof. Fix $x = e^{hi}$ and $y = re^{ki}$ where $r > 0$ and $0 < h \leq k < \theta$. Clearly, $x^* = x = e^{hi}$ and $y^* = (1/r)e^{ki}$. Suppose first that $\theta \leq \pi$. By the known solution to Heron’s problem, the infimum $\inf_{z \in \partial S_\theta} (|x - z| + |z - y|)$ is $\min\{|\bar{x} - y|, |x - y'|\}$, where y' is the point y reflected over the left side of the sector θ . Clearly,

$$\begin{aligned} |\bar{x} - y| \leq |x - y'| &\Leftrightarrow |e^{-hi} - re^{ki}| \leq |e^{hi} - re^{(2\theta - k)i}| \\ \Leftrightarrow |1 - re^{(h+k)i}| \leq |1 - re^{(2\theta - h - k)i}| &\Leftrightarrow h + k \leq 2\theta - h - k \\ \Leftrightarrow (h + k)/2 \leq \theta/2. \end{aligned}$$

By symmetry, we may assume that $(h + k)/2 \leq \theta/2$ without loss of generality. Note that it follows from above that not only $\inf_{z \in \partial S_\theta} (|x - z| + |z - y|) = |\bar{x} - y|$ but also $\inf_{z \in \partial S_\theta} (|x^* - z| + |z - y^*|) = |\bar{x}^* - y^*|$. Now,

$$\begin{aligned} s_{S_\theta}(x, y) &= \frac{|x - y|}{|\bar{x} - y|} = \frac{|1 - re^{(k-h)i}|}{|1 - re^{(k+h)i}|} = \frac{|1 - re^{(h-k)i}|}{|1 - re^{-(k+h)i}|} = \frac{|r - e^{(k-h)i}|}{|r - e^{(k+h)i}|} \\ &= \frac{|1 - (1/r)e^{(k-h)i}|}{|1 - (1/r)e^{(k+h)i}|} = \frac{|x^* - y^*|}{|\bar{x}^* - y^*|} = s_{S_\theta}(x^*, y^*). \end{aligned}$$

Consider now the case where $\theta > \pi$. If $k - h \geq \pi$, then $s_{S_\theta}(x, y) = 1 = s_{S_\theta}(x^*, y^*)$ always so suppose that $k - h < \pi$ instead. This leaves us three possibilities. If $(h + k)/2 \leq \pi/2$, then $(h + k)/2 < \theta/2$ and

$$s_{S_\theta}(x, y) = \frac{|x - y|}{|\bar{x} - y|} = \frac{|x^* - y^*|}{|x^* - y^*|} = s_{S_\theta}(x^*, y^*),$$

just like above. By symmetry, $s_{S_\theta}(x, y) = s_{S_\theta}(x^*, y^*)$ also if $(k + h)/2 \geq \theta - \pi/2$. If $\pi/2 < (k + h)/2 < \theta - \pi/2$ instead, then

$$\begin{aligned} s_{S_\theta}(x, y) &= \frac{|x - y|}{|x| + |y|} = \frac{|1 - re^{(k-h)i}|}{1 + r} = \frac{|1 - (1/r)e^{(k-h)i}|}{1 + 1/r} \\ &= \frac{|x^* - y^*|}{|x^*| + |y^*|} = s_{S_\theta}(x^*, y^*). \end{aligned}$$

□

Theorem 4.8. *If $\theta \in [\pi, 2\pi)$ and $f^* : S_\theta \rightarrow S_\theta$ is the mapping $f^*(x) = x/|x|^2$, the Lipschitz constant $Lip(f^*|S_\theta)$ for the t -metric is 2.*

Proof. It follows from Theorems 4.7 and 3.8(3) that

$$\frac{t_{S_\theta}(x, y)}{2} \leq t_{S_\theta}(x^*, y^*) \leq 2t_{S_\theta}(x, y)$$

for all $x, y \in S_\theta$. Since for $x = e^{hi}$ and $y = re^{\pi i/2}$ with $h < \pi/2$ and $r > 0$,

$$\lim_{h,r \rightarrow 0^+} \frac{t_{S_\theta}(x^*, y^*)}{t_{S_\theta}(x, y)} = \lim_{h,r \rightarrow 0^+} \left(\frac{\sqrt{1 + r^2 - 2r \cos(\pi/2 - h)} + r \sin(h) + 1}{\sqrt{1 + r^2 - 2r \cos(\pi/2 - h)} + \sin(h) + r} \right) = 2,$$

and it follows that

$$\sup \left\{ \frac{t_{S_\theta}(x^*, y^*)}{t_{S_\theta}(x, y)} \mid x, y \in S_\theta, x \neq y, \theta \in [\pi, 2\pi) \right\} = 2.$$

□

5. Comparison of Metric Balls

Next, we will graphically demonstrate the differences and similarities between the various metrics considered in this paper by drawing boundaries of balls centered at the same point but with different radii for each metric. In all of the figures of this section, the domain $G \subset \mathbb{R}^2$ is a regular five-pointed star and the circles have the radii $r = 1/10, \dots, 9/10$. The center of these circles is in the center of G in the first figures, and then off the center in the rest of the figures. All the figures in this section were drawn by using the contour plot function `contour` in R-Studio and choosing a grid of the size $1,000 \times 1,000$ test points. While we graphically only inspect circles and disks, we will also prove some properties for the n -dimensional metric balls.

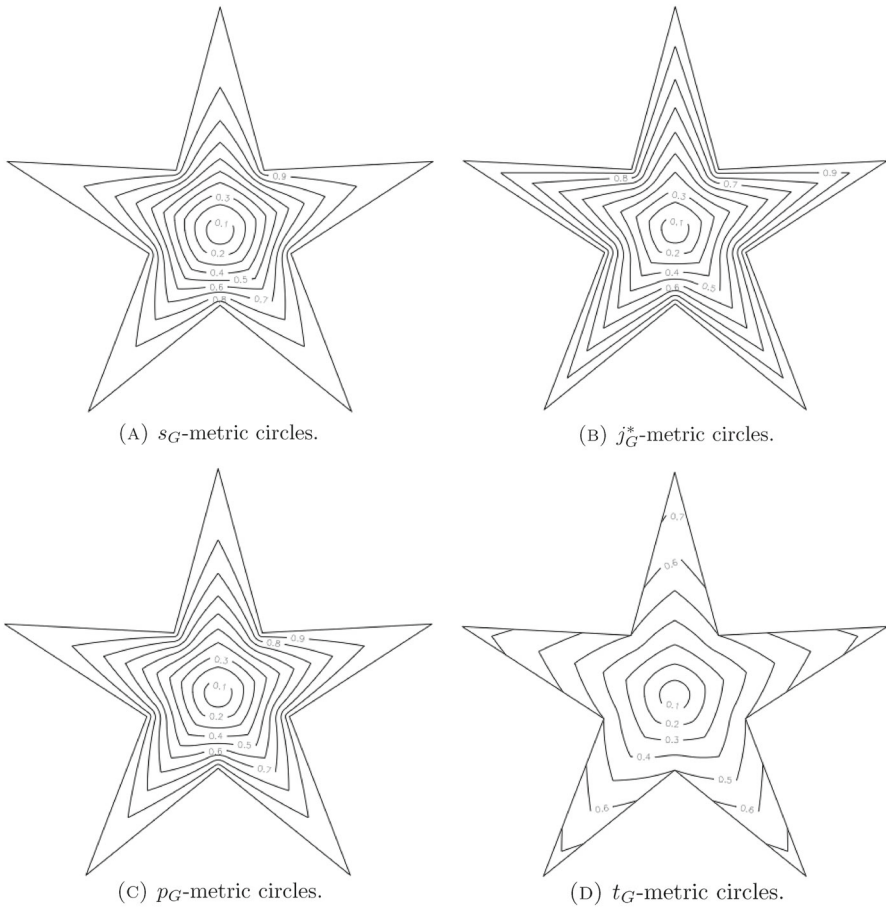


FIGURE 1. Circles in a five-pointed star domain with different metrics

For several hyperbolic type metrics, the metric balls of small radii resemble Euclidean balls, but the geometric structure of the boundary of the domain begins to affect the shape of these balls when their radii grow large enough, see [7, Ch. 13, pp. 239-259]. By analysing this phenomenon more carefully, we can observe, for instance, that the balls are convex with radii less than some fixed $r_0 > 0$ in the case of some other metrics, see [7, Thm 13.6, p. 241; Thm 13.41 p. 256; Thm 13.44, p. 258]. From the figures of this section, we see that the four metrics studied here share this same property. In particular, we notice that, while the metric disks with small radii are convex and round like Euclidean disks, the metric circles with larger radii are non-convex and have

corner points. By a corner point, we mean here such a point on the circle arc where no tangent exists.

In the following theorem, we will prove a property that can be seen from Figs. 1c, d and 2c, d.

Theorem 5.1. *If the domain G is a polygon, then the corner points of the circles $S_p(x, r)$ and $S_t(x, r)$ are located on the angle bisectors of G .*

Proof. Suppose G has sides l_0 and l_1 that have a common endpoint k . Fix $x \in G$ and choose some point $y \in G$ so that k is the vertex of G that is closest to y and there is no other side closer to y than l_0 and l_1 . Thus, $d_G(y) = \min\{d(y, l_0), d(y, l_1)\}$ and, for a fixed distance $|x - y|$, $d_G(y)$ is at maximum when $d(y, l_0) = d(y, l_1)$. The condition $d(y, l_0) = d(y, l_1)$ is clearly fulfilled when y is on the bisector of $\angle(l_0, l_1)$ and, the greater the $d_G(y)$, the smaller the distances $p_G(x, y)$ and $t_G(x, y)$ are now. Consequently, if the circle $S_p(x, r)$ or $S_t(x, r)$ has a corner point, it must be located on an angle bisector of G . \square

However, it can be seen from Fig. 2a, b that the circles with the metrics s_G and j_G^* can have corner points also elsewhere than on the angle bisectors of the domain G . We also notice that the circles in Fig. 2b clearly differ from those in Fig. 2a. This can be described with the concept of starlikeness, which is a looser form of convexity. Namely, a set K is *starlike* with respect to a point $x \in K$ if and only if the segment $[x, y]$ belongs to K fully for every $y \in K$. In particular, the five-pointed star domain is starlike with respect to its center. The disks by the metrics j_G^* and t_G (Fig. 2b, d) are clearly not starlike and, even if it cannot be clearly seen from Fig. 2c, there are disks drawn with the point pair function p_G that are not starlike.

Lemma 5.2. *There exist disks $B_{j^*}(x, r)$, $B_p(x, r)$, and $B_t(x, r)$ that are not starlike with respect to their center.*

Proof. Consider the domain $G = \mathbb{H}^2 \cup \{z \in \mathbb{C} \mid -1 < \operatorname{Re}(z) < 1, -3 < \operatorname{Im}(z) \leq 0\}$. Fix $x = -2i$ and $y = 3 + i$. Clearly, $d_G(x) = d_G(y) = 1$ and $|x - y| = 3\sqrt{2}$. Consequently,

$$j_G^*(x, y) = t_G(x, y) = \frac{3}{3 + \sqrt{2}} < 0.7, \quad p_G(x, y) = \frac{3}{\sqrt{11}} < 0.91.$$

The segment $[x, y]$ does not clearly belong to G fully and no disk in G can contain this segment. However, its end point y is clearly included in the disks $B_{j^*}(x, 0.7)$, $B_t(x, 0.7)$ and $B_p(x, 0.91)$. Thus, we have found examples of non-starlike disks. \square

There are no disks or balls like this for the triangular ratio metric.

Lemma 5.3. [7, p. 206] *The balls $B_s(x, r)$ in any domain $G \subsetneq \mathbb{R}^n$ are always starlike with respect to their center x .*

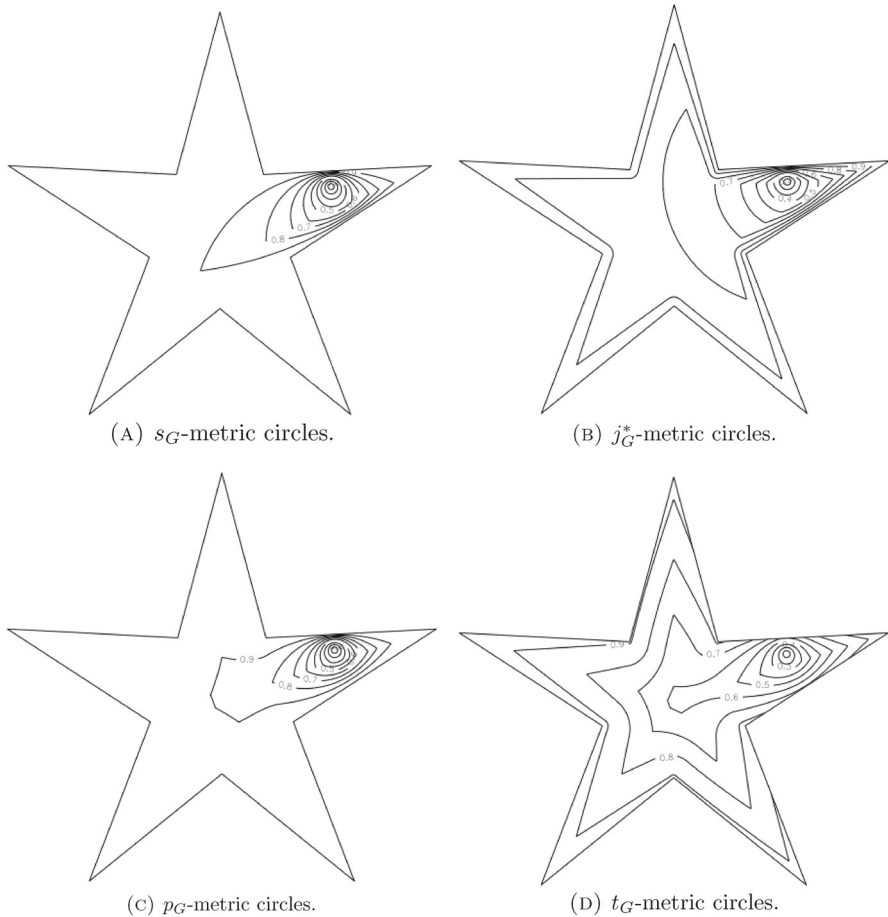


FIGURE 2. Circles in a five-pointed star domain with different metrics

For several common hyperbolic type metrics η_G , the closed ball $\overline{B_\eta(x, M)}$ with $M = \eta_G(x, y)$ and $x, y \in G$ is always a compact subset of the domain G , see [7, p. 79]. For instance, the hyperbolic metric ρ_G has this property [7, p. 192]. As can be seen from the figures, the j^* -metric, the triangular ratio metric and the point pair function share this property, too.

Lemma 5.4. *The balls $B_{j^*}(x, r)$, $B_p(x, r)$ and $B_s(x, r)$ touch the boundary of the domain $G \subsetneq \mathbb{R}^n$ if and only if $r = 1$.*

Proof. If the ball $B_\eta(x, r)$, $\eta_G \in \{j_G^*, p_G, s_G\}$, touches the boundary of G , then there is some point $y \in B_\eta(x, r)$ with $d_G(y) \rightarrow 0^+$ and $\eta_G(x, y) \rightarrow 1^-$. Thus, we need to just prove that the balls with radius 1 always touch the

boundary. Consider then the line segment $[x, z]$ between a point $x \in G$ and a point $z \in \partial G$ such that $|x - z| = d_G(x)$. For $\eta_G \in \{j_G^*, p_G\}$, the ball $B_\eta(x, 1)$ must include all the points $[x, z] \cap G$ because $\eta_G(x, y) < 1$ by definition for all $y \in G$, and thus there is some point $y \in [x, z]$ with $d_G(y) \rightarrow 0^+$. The triangular ratio metric $s_G(x, y)$ is 1 if and only if $|x - y| = |x - u| + |u - y|$ for some $u \in \partial G$ or, equivalently, $[x, y] \cap \partial G \neq \emptyset$. However, if $|x - z| = d_G(x)$, then $[x, z] \cap \partial G = \{z\}$ and, for all points $y \in [x, z] \cap G$, $s_G(x, y) < 1$. Thus, there is some point $y \in [x, z]$ with $d_G(y) \rightarrow 0^+$ and this point y is included in the ball $B_s(x, 1)$. \square

However, the t -metric differs from the hyperbolic type metrics in this aspect: the closure of a t -metric ball is a compact set, if and only if the radius of the ball is less than $1/2$.

Theorem 5.5. *The balls $B_t(x, r)$ touch the boundary of the domain $G \subsetneq \mathbb{R}^n$ if and only if $r \geq \frac{1}{2}$.*

Proof. If $B_t(x, r)$ touches the boundary, there must be some $y \in B_t(x, r)$ such that $d_G(y) \rightarrow 0^+$. Since $d_G(x) \leq |x - y| + d_G(y)$, it follows that $t_G(x, y)$ is equal to or greater than the limit value

$$\frac{|x - y|}{|x - y| + |x - y| + 0 + 0} = \frac{1}{2}.$$

Thus, only balls $B_t(x, r)$ with a radius $r \geq \frac{1}{2}$ can touch the boundary of G .

Let us yet prove that the balls $B_t(x, \frac{1}{2})$ always touch the boundary of G . Fix $x \in G$ and $z \in \partial G$ so that $|x - z| = d_G(x)$. For all points $y \in [x, z] \cap G$,

$$t_G(x, y) = \frac{|x - y|}{|x - y| + d_G(x) + d_G(x) - |x - y|} = \frac{|x - y|}{2d_G(x)} < \frac{1}{2}.$$

Thus, there is some point $y \in [x, z]$ with $d_G(y) \rightarrow 0^+$ and it is included in the ball $B_t(x, \frac{1}{2})$. \square

The result above is visualized in Figs. 1d and 2d.

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conflict of interest On behalf of all authors, the corresponding author states that there is no conflict of interest

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