Minimum Number of Input Clues in Robust Information Retrieval

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Abstract

Information retrieval in associative memories was considered recently by Yaakobi and Bruck in [15]. In their model, a stored information unit is retrieved using input clues. In this paper, we study the problem where at most s ($s \ge 0$) of the received input clues can be false and we still want to determine the sought information unit uniquely. We use a coding theoretical approach to estimate the maximum number of stored information units with respect to a given s. Moreover, optimal results for the problem are given, for example, in the infinite king grid. We also discuss the problem in the class of line graphs where a characterization and a connection to k-factors is given.

Keywords: Information retrieval, associative memory, robustness, Johnson bound, $k\text{-}\mathrm{factor}$

1 Introduction

Let G = (V, E) be a simple, undirected and connected graph. The graphic distance d(x, y) between vertices $x \in V$ and $y \in V$ is the number of edges in any shortest path between them. If vertices x and y are adjacent, we use the notation $x \sim y$. The degree of a vertex x, denoted by deg(x), is the number of vertices adjacent to x. The minimum degree of G is $\delta = \delta(G)$.

Information retrieval in an associative memory is modeled as follows. Let G = (V, E) be a graph where the vertices correspond to the memory entries containing the stored information units. The edges between the vertices represent associations between information units and two vertices $x, y \in V$ are said to be *t*-associated if $d(x, y) \leq t$. The set of *t*-associated vertices to *x* constitutes a ball of radius *t* centered at *x*, that is,

$$B_t(x) = \{ y \in V \mid d(x, y) \le t \}.$$

If t = 1, we omit t and write the closed neighbourhood $B_1(x) = B(x)$.

The information retrieval in the memory is performed based on associations as follows. We have a *reference set* $C \subseteq V$. We retrieve the sought information unit $x \in V$ by receiving *input clues* from C one after another (until we can determine x uniquely). Moreover, if the input clues are t-associated to x then we say that they are *correct* input clues and, if they are not *t*-associated to x then they are called *false* input clues. We assume that there are at most *s* false input clues for some fixed $s \ge 0$. The set

$$I_t(x) = I_t(C; x) = B_t(x) \cap C$$

is the set of all possible correct input clues for $x \in V$. Again, if t = 1, we write $I_1(x) = I(x)$. Next we consider when it is possible to find a sought information unit uniquely assuming there are at most s false input clues.

If $|I_t(x) \setminus I_t(y)| \leq s$ for some $y \in V$, $x \neq y$, then we cannot retrieve x without ambiguity. Namely, even receiving all the possible correct input clues in $I_t(x)$, we cannot determine x uniquely. Indeed, in spite of receiving $I_t(x)$, y could also be the sought information unit, because we may have received $I_t(x) \cap I_t(y)$ correct input clues for y and the rest $I_t(x) \setminus I_t(y)$ (at most s of them!) are false clues (regarding y). Hence, based on the input clues in $I_t(x)$, the sought information unit could be either x or y (and we cannot expect to receive any more clues for x).

If $|I_t(x) \setminus I_t(y)| \ge s+1$ for every $y \in V$, $y \ne x$, then we can determine x uniquely. Moreover, in order to determine x, it is enough to receive any

$$m_t(C; x, s) = \max_{x \neq y} |I_t(x) \cap I_t(y)| + s + 1$$

correct clues from $I_t(x)$. Namely, suppose we have received (at least) such amount of correct clues together with at most s false clues. Denote the set of received input clues by U. So $|U \cap I_t(x)| \ge m_t(C; x, s)$ and $|U \setminus I_t(x)| \le s$. If now some $y \in V$ would be the sought information unit instead of x, then, by the definition of $m_t(C; x, s)$, there are at least s + 1 input clues in U which are not in $I_t(y)$. Hence y cannot be the sought information unit, because there would be at least s + 1 false input clues regarding y and we allowed at most s.

In the sequel, we assume that we can retrieve all information units in V without ambiguity, so we require from the reference set C that for all distinct vertices $x, y \in V$ we have

$$|I_t(C;x) \setminus I_t(C;y)| \ge s+1.$$
(1)

Recall that we may receive up to s false clues. Therefore, in the worst case, we need to listen to at most $m_t(C; x, s) + s$ input clues in order to determine x uniquely. It is natural to require that there is some fixed upper bound m on number of input clues needed to determine any information unit. This leads to the following definition.

Definition 1. Let G = (V, E) and $C \subseteq V$. We say that a pair (G, C) is a sequential (t, m)-associative memory robust against at most s false input clues with the reference set C if (1) holds for all distinct vertices $x, y \in V$ and

$$m_t(C; x, s) + s \le m$$
 for any $x \in V$.

In short, the sequential (t, m)-associative memory robust against at most s false input clues is called s-robust $SAM_G(t, m)$. We also say that C gives an s-robust $SAM_G(t, m)$ if it is a reference set of the memory. In the sequel, we call the reference set a code and its elements codewords.

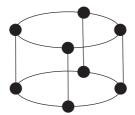


Figure 1: The graph $G_8 = (V, E)$. The set C = V gives a 1-robust $\mathcal{SAM}_{G_8}(1, 5)$.

Naturally, we would like to find the sought information unit with as small number of input clues as possible, so we prefer a code (a reference set) $C \subseteq V$ giving an *s*-robust $SAM_G(t,m)$ with as small value of

$$m = \max_{x \neq y} \{ |I_t(C;x) \cap I_t(C;y)| \} + 2s + 1.$$
(2)

as possible.

Example 2. Consider the graph G_8 in Figure 1. The whole vertex set C = V of G_8 is a code giving a 1-robust $\mathcal{SAM}_{G_8}(1,5)$ as shown next. The graph is 3-regular and for C = V we have $I(x) = I(V; x) = B(x) \cap V = B(x)$. Hence |I(x)| = 4 for all $x \in V$ and it is easy to check that $|I(x) \cap I(y)| \leq 2$ for any $x, y \in V, x \neq y$. These observations yield $|I(x) \setminus I(y)| \geq 2$ for distinct vertices $x, y \in V$. Hence the condition (1) is satisfied when s = 1. Using (2) we get m = 5, as claimed.

Let a code C give an s-robust $SAM_G(t, m)$. As discussed, we listen to clues (sequentially) one after another in order to find the sought information unit $x \in V$. Suppose we have received clues $U \subseteq C$. We discard any $y \in V$ such that $|U \setminus I_t(y)| \ge s + 1$, since it cannot be the sought information unit (too many false clues regarding y). It is guaranteed by C, that after receiving at most mclues, we are left with one single non-discarded vertex in V. This is the sought information unit x.

The model of information retrieval in an associative memory discussed above was introduced by Yaakobi and Bruck [15] without the notion of false clues (i.e., they considered the case s = 0). In this paper, we allow the possibility of at most s false clues. Besides [15], the information retrieval has also been studied in [16], [6], [7], [9] and [8] — again when s = 0. Related codes concerning (1) can also be found in [5, Theorem 3]. Apart from the information retrieval in an associative memory, the concept of Definition 1 has applications to Levenshtein's sequences reconstruction problem (see [10, 15, 8]) and to the following problem of RF-based localization.

Remark 3. Consider a sensor network monitoring with RF-based localization, which is discussed in [4, 14] for indoor environments. Sensors in a building are mapped to vertices of a graph G = (V, E) and a pair of vertices is connected by an edge if the two corresponding sensors are within each other's communication range. A small portion of all sensors $C \subseteq V$ are kept active while the others can be put in energy-saving mode. The system periodically broadcasts

ID packets from the active sensors. Suppose C gives an s-robust $SAM_G(t, m)$. An observer can determine her location $x \in V$ from the set of ID packets U that she receives even if there were s false ID packets in U caused by changes in a harsh environment [14] (like door openings permitting ID package from an active sensor, which is not normally at the communication range from x). For more details, see [4, 14].

The paper is organized as follows. In Section 2, we provide optimal results for codes giving an s-robust $SAM_{\mathcal{K}}(t,m)$ in the king grid \mathcal{K} , which is a widely studied graph (see, for example, [3] and numerous other papers in [11]). The Section 3 discusses a lower bound on the number of input clues m when t = 1. We use a method from coding theory in Section 4 to estimate the number of possible information units when s is given. It is also shown that this estimate is attained for a family of strongly regular graphs \mathcal{A}^r , $r \geq 1$. In the last section, we show that in the class of *line graphs* we can characterize the structure of s-robust codes. We also give optimal results with the aid of suitable k-factors.

2 The infinite king grid

In this section, we consider as the underlying graph the infinite two-dimensional square lattice with diagonals (illustrated in Figure 2). Its vertex set is $V = \mathbb{Z} \times \mathbb{Z} = \mathbb{Z}^2$ and two vertices $u = (u_1, u_2)$ and $v = (v_1, v_2)$ are adjacent if their Euclidean distance is at most $\sqrt{2}$, that is, $|u_1 - v_1| \leq 1$ and $|u_2 - v_2| \leq 1$. We call the resulting infinite graph the *king grid* and denote it by \mathcal{K} .

Observe that the ball of radius t centered at $u = (u_1, u_2)$ in \mathcal{K} is a $(2t+1) \times (2t+1)$ -square (see Figure 2(a))

$$B_t(u) = \{(x, y) \in \mathbb{Z}^2 \mid |u_1 - x| \le t, |u_2 - y| \le t\}.$$

The next theorem provides the optimal results in the king grid \mathcal{K} for any $t \geq 1$ and (all possible values of) s.

Theorem 4. For each $t \ge 1$ and $0 \le s \le 2t$, there exists a code *C* giving an *s*-robust $SAM_{\mathcal{K}}(t,m)$ with m = 2t(s+1)+2s+1. Moreover, this is the smallest possible *m* in the sense that for any code giving an *s*-robust $SAM_{\mathcal{K}}(t,m)$ we have $m \ge 2t(s+1)+2s+1$.

Proof. Denote $S_s = \{0, 1, 2, \dots, s\}$. Let

$$C_{s,t} = \{(a,b) \in \mathbb{Z}^2 \mid a-b \equiv i \pmod{2t+1} \text{ for } i \in S_s\}.$$

We have illustrated $C_{1,2}$ in Figure 2(b). We will verify using (1) and (2) that $C_{s,t}$ gives an s-robust $SAM_{\mathcal{K}}(t,m)$ with m = 2t(s+1) + 2s + 1.

First we consider (1). Let $x = (x_1, x_2) \in \mathbb{Z}^2$ and $y = (y_1, y_2) \in \mathbb{Z}^2$, $x \neq y$.

Assume first that $x_1 < y_1$. Then $B_t(x) \setminus B_t(y)$ contains the set of 2t + 1 vertically consecutive vertices $\{x + (-t, -t + j) \mid j = 0, 1, \dots, 2t\}$. Clearly, $s + 1 = |S_s|$ of these consecutive points satisfies the congruence which defines $C_{s,t}$. Hence, $|I(x) \setminus I(y)| \ge s + 1$ as required in (1).

The case $x_1 > y_1$ is analogous to the previous one, so it suffices to assume that $x_1 = y_1$. Then either $x_2 < y_2$ or $x_2 > y_2$. Suppose $x_2 < y_2$ (the case $x_2 > y_2$ is similar). Now $B_t(x) \setminus B_t(y)$ contains the set of the following 2t + 1

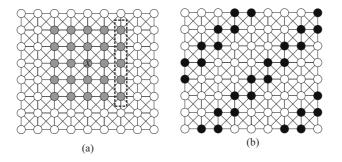


Figure 2: (a) The gray vertices constitute the ball $B_2(x)$. The dashed box illustrates $P_0(x)$. (b) The black vertices constitute the code $C_{1,2}$.

horizontally consecutive points $\{x + (-t + j, -t) \mid j = 0, 1, ..., 2t\}$ and s + 1 of these belong to $C_{s,t}$ giving again $|I(x) \setminus I(y)| \ge s + 1$.

Next we determine m using (2). If $x_1 < y_1$, then $B_t(x) \cap B_t(y)$ is a subset of $B_t(x) \cap B_t(x + (1,0))$. The set $B_t(x) \cap B_t(x + (1,0))$ consists of 2t disjoint subsets $P_i(x)$, $i = 0, 1, \ldots, 2t - 1$ where (see Figure 2(a))

$$P_i(x) = \{x + (t - i, -t + j) \mid j = 0, 1, 2, \dots, 2t\}$$

Each of these subsets $P_i(x)$ consists of 2t + 1 vertically consecutive points, so exactly s + 1 of them belongs to $C_{s,t}$. Consequently, $|I_t(x) \cap I_t(y)| \leq 2t(s+1)$. The case $x_1 > y_1$ is analogous. If $x_1 = y_1$ we use horizontal disjoint subsets instead of $P_i(x)$ and the same argument works. Therefore, by (2), we have m = 2t(s+1) + 2s + 1.

Finally, we estimate m for any code D giving an s-robust $SAM_{\mathcal{K}}(t,m)$. Now the vertical subsets $P_i(x)$ each contain $at \ least \ s+1$ codewords of D due to (1), which must be satisfied by D. Thus $|I_t(D;x) \cap I_t(D;x+(1,0))| \ge 2t(s+1)$. This yield the estimate on $m \ge 2t(s+1) + 2s + 1$ for D.

3 Lower bound on the number of input clues

The next result discusses the relation between the number of input clues m and the robustness $s \ge 0$ when the radius t = 1.

Theorem 5. Let G be a d-regular graph and $\Omega = \min_{x \sim y} |B(x) \cap B(y)|$. If C gives an s-robust $SAM_G(1,m)$, then

$$m \ge \frac{(s+2)\Omega}{d} + 2s + 1. \tag{3}$$

Proof. Let C give an s-robust $SAM_G(1,m)$ in G = (V, E). First we will show that

$$|C| \ge \frac{|V|(s+2)}{d}.\tag{4}$$

• For each non-codeword $x \in V \setminus C$, we have $|I(x)| \ge s + 2$. Indeed, by (1), we have $|I(x)| \ge s + 1$. Choose $c \in I(x)$. The set I(x) contains the set

 $I(x) \setminus I(c)$ and in addition at least the codeword c. By (1), $|I(x) \setminus I(c)| \ge s+1$ and we are done. For a codeword $x \in C$ we have $|I(x)| \ge s+3$. Indeed, let $c' \in I(x), x \neq c'$. Now $I(x) \setminus I(c')$ contains neither x nor c' (and I(x) contains both of them), which gives the claim since $|I(x) \setminus I(c')| \ge s+1$.

Counting in two ways the number N of pairs (x, c) where $x \in V$ and $c \in C$ with $d(x, c) \leq 1$ we get

$$|C|(d+1) = N \ge |V \setminus C|(s+2) + |C|(s+3).$$

This yields the bound (4).

Now we will prove the claimed bound (3) on m. Since each intersection $I(x) \cap I(y)$, where $x \sim y$, contains by (2) at most m - 2s - 1 codewords of C, we obtain (since G is d-regular) that

$$(m-2s-1)|V|d \ge \sum_{\substack{x,y \in V \\ x \sim y}} |I(x) \cap I(y)|.$$

Next we will verify the estimate

$$\sum_{\substack{x,y \in V \\ x \sim y}} |I(x) \cap I(y)| \ge |C| d\Omega.$$

Indeed, for a fixed $c \in C$ let us count the number of pairs x and y such that $x \sim y$ and $c \in I(x) \cap I(y)$. If x = c, then there exist d such pairs (x, y). If $x \neq c$, there are at least $d(\Omega - 1)$ such pairs (notice that $x \neq y$). Consequently, the number of pairs it at least $d\Omega$ for each $c \in C$.

The two inequalities above yield $(m - 2s - 1)|V| \ge |C|\Omega$. Combining this with (4) gives

$$(m-2s-1)|V| \ge \frac{|V|(s+2)\Omega}{d}$$

from which the assertion follows.

The lower bound (3) is attained, for example in the case of Example 2. There we observed that C = V gives a 1-robust $SAM_{G_8}(1,5)$. In G_8 we have $\Omega = 2$ and d = 3. Consequently, the bound $m \geq 5$ provided by (3) is achieved by the code C.

4 A family of strongly regular graphs

We start the section by discussing in Theorem 6 the relation between the number of information units |V| and the robustness s using an approach from coding theory. Then we show that the bound (5) is attained for a family of strongly regular graphs \mathcal{A}^r , $r \geq 1$. Finally, we construct codes (see Example 8 and Theorem 9) giving an s-robust $\mathcal{SAM}(1,m)$ in the graph \mathcal{A}^r .

Let *n* and *w* be positive integers where $0 \le w \le n$. Denote the binary field by $\mathbb{F} = \{0, 1\}$ and the Cartesian product $\mathbb{F}^n = \mathbb{F} \times \mathbb{F} \times \cdots \times \mathbb{F}$ (*n* times). The elements of \mathbb{F}^n are called *words* and a nonempty subset *C* of \mathbb{F}^n is called a *code*. For $x = x_1 x_2 \dots x_n \in \mathbb{F}^n$, we define the *(Hamming) weight* w(x) as the number of coordinates with 1 in x. Let binary Johnson space $\mathbb{F}^{n,w}$ consists of all the words in \mathbb{F}^n with weight exactly w. We endow the space with the Hamming distance d(x, y) which is the number of bits where words x and y differ.

A subset C of the Johnson space $\mathbb{F}^{n,w}$ is called a *constant weight code* and its elements are called *codewords*. We define further A(n, d, w) to be the greatest cardinality of a constant weight code in which the distinct codewords have Hamming distance at least d apart.

Theorem 6. Let G = (V, E) be a k-regular graph. If C gives an s-robust $SAM_G(1,m)$, then

$$|V| \le A(|V|, 2(s+1), k+1)$$

In particular,

$$|V| \le \left\lfloor \frac{(s+1)|V|}{(k+1)^2 - (k+1)|V| + (s+1)|V|} \right\rfloor$$
(5)

provided that the denominator is positive.

Proof. Let $C = \{c_1, c_2, \ldots, c_{|C|}\}$ give an *s*-robust $\mathcal{SAM}_G(1, m)$ in a *k*-regular graph G = (V, E). Let us write the sets $I(C; x), x \in V$, using binary words $b(x) = b_1^x b_2^x \ldots b_{|C|}^x \in \mathbb{F}^{|C|}$ in the following way:

$$b_i^x = \begin{cases} 1 & \text{if } c_i \in B(x), \\ 0 & \text{otherwise.} \end{cases}$$

Let us denote by $\mathcal{B}(C)$ the binary code obtained in this way. Obviously, the distance between any two words of $\mathcal{B}(C)$ is at least 2(s+1), due to (1).

Because C gives an s-robust $SAM_G(1,m)$, then also V gives an s-robust $SAM_G(1,m')$ for some $m' \geq m$. Now, since G is k-regular, the code $\mathcal{B}(V)$ is a constant weight code with weight k + 1 and the the distance between any two codewords of $\mathcal{B}(V)$ is still at least 2(s + 1). Clearly, the number of codewords in $\mathcal{B}(V)$ equals |V|. Consequently,

$$|V| \le A(|V|, 2(s+1), k+1).$$

For the second claim (5) we use the Johnson bound [12, p. 525]

$$A(n, 2\delta, w) \le \left\lfloor \frac{\delta n}{w^2 - wn + \delta n} \right\rfloor$$

if the denominator is positive.

The following theorem 7 shows that the bound of the previous theorem can be attained.

Let us first introduce some definitions and notations. A graph G = (V, E) is called *strongly regular* with parameters (n, k, λ, μ) if |V| = n, G is k-regular and any two adjacent vertices have exactly λ common neighbours and any two nonadjacent vertices have exactly μ common neighbours. See [1] for more information.

Let $\mathbb{A} = \{1, 2, 3, 4\}$ and $r \geq 1$. We will focus on a graph \mathcal{A}^r where the vertex set is the Cartesian product $\mathbb{A}^r = \mathbb{A} \times \cdots \times \mathbb{A}$ (r times) and two different vertices $i_1 \dots i_r \in \mathbb{A}^r$ and $j_1 \dots j_r \in \mathbb{A}^r$ are adjacent if and only if the number

of coordinates ρ such that $i_{\rho} + j_{\rho} = 5$ is even. For any $r \ge 1$, it is known [2] that \mathcal{A}^r is a strongly regular graph with parameters

$$(2^{2r}, 2^{2r-1} + 2^{r-1} - 1, 2^{2r-2} + 2^{r-1} - 2, 2^{2r-2} + 2^{r-1}).$$

Theorem 7. Let $r \geq 1$. The code $C = \mathbb{A}^r$ gives a $(2^{2r-2}-1)$ -robust $\mathcal{SAM}_{\mathcal{A}^r}(1, 3 + 2^{2r-2} + 2^{r-1} - 1)$, which attains the bound (5).

Proof. Consider the graph \mathcal{A}^r and choose as the code C the whole set of vertices. Since in the graph \mathcal{A}^r the cardinality of the ball B(x) equals $2^{2r-1} + 2^{r-1}$ for all x and the intersection $|B(x) \cap B(y)| = \lambda + 2 = \mu = 2^{2r-2} + 2^{r-1}$ for any x and y with $1 \leq d(x, y) \leq 2$, the set $B(x) \setminus B(y)$ contains 2^{2r-2} elements. Hence it follows that C is a $(2^{2r-2} - 1)$ -robust $\mathcal{SAM}_{\mathcal{A}^r}(1, m)$ with

$$m = 3 \cdot 2^{2r-2} + 2^{r-1} - 1.$$

Now clearly, $|\mathbb{A}^r| = 4^r$ and it is easy to check that the right-hand side of (5) equals 4^r also.

Theorem 7 gives the maximum value for s of an s-robust SAM(1,m) in A^r . Next we consider smaller values of s in the following example and in Theorem 9.

Example 8. In this example, we provide codes giving an s-robust $SAM_{A^r}(1,m)$ for r = 2. (For r = 1, A^1 is a 4-cycle, and there are clearly no other values of s except the s = 0 of the previous theorem). Let

$$C_0 = \{14, 22, 23, 24, 31, 33, 34, 41, 42, 44\},\$$

$$C_1 = \{13, 14, 23, 24, 31, 32, 33, 34, 41, 42, 43, 44\}$$

and $C_2 = \mathbb{A}^2 \setminus \{11\}$. The previous codes C_s are such *s*-robust $\mathcal{SAM}_{\mathcal{A}^2}(1, m_s)$ codes that (as computer searches show) they have the smallest values of (2), namely, $m_0 = 6$, $m_1 = 9$ and $m_2 = 11$. In addition to these, we have the code $C = \mathbb{A}^2$ of the previous theorem giving m = 13.

Next we provide an approach to give codes when r is general. Let C be a code giving an *s*-robust SAM(1,m) in A^r , $r \ge 1$. In the following theorem, we provide a method to obtain using C a robust SAM(1,m') for the larger graph A^{r+1} . Let $F \subseteq A^r$. Denote by

$$\operatorname{App}(F,i) = \{x_1 \dots x_r i \mid x_1 \dots x_r \in F\} \subseteq \mathbb{A}^{r+1}$$

the set where we have appended the last fixed coordinate $i \in \mathbb{A}$.

Theorem 9. Let $r \ge 1$ and C give an s-robust SAM(1,m) in A^r . Denote $i_{max} = \max\{|I(x)| \mid x \in \mathbb{A}^r\}, i_{min} = \min\{|I(x)| \mid x \in \mathbb{A}^r\}$ and $l = \min\{|I(x) \cup I(y)| \mid x, y \in \mathbb{A}^r, x \ne y\}$. Then the code

$$D = App(C, 1) \cup App(C, 2) \cup App(C, 3)$$

gives an S-robust SAM(1,m') in A^{r+1} with parameters

$$S = \min\{2(s+1), i_{min}, |C| - i_{max}\} - 1$$

and

$$m' = \max\{3(m-2s-1), 2i_{max}, 2(m-2s-1) + |C| - l\} + 2S + 1.$$

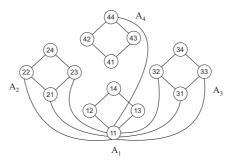


Figure 3: The graph \mathcal{A}^1 is a 4-cycle. In the figure there are the vertices of the graph \mathcal{A}^2 given as the four "copies" of \mathcal{A}^1 . The vertices between the different layers A_i are not given except those that are incident with 11 indicating B(11).

Proof. Let us first consider the structure of \mathcal{A}^{r+1} with the aid of \mathcal{A}^r . We divide the set of vertices \mathbb{A}^{r+1} into four layers depending on the last coordinate, namely,

$$\mathbb{A}^{r+1} = A_1 \cup A_2 \cup A_3 \cup A_4$$

where

$$A_i = \{x_1 x_2 \dots x_r i \mid x_1 x_2 \dots x_r \in \mathbb{A}^r\}$$

for any i = 1, 2, 3, 4. We also divide a vertex $x \in \mathbb{A}^{r+1}$ into two parts, namely, x = x'i where $x' \in \mathbb{A}^r$ and $i \in \mathbb{A}$.

Next we consider a ball B(x) in \mathbb{A}^{r+1} and examine its parts $B(x) \cap A_j$ in the layers j = 1, 2, 3, 4:

• Denote by $\tilde{B}(x')$ be the ball centered at x' in the smaller graph \mathcal{A}^r for any $x = x'i \in \mathbb{A}^{r+1}$. The ball B(x) = B(x'i) consists of the four parts in the different layers (see Figure 3) where

$$B(x'i) \cap A_j = \begin{cases} \operatorname{App}(\tilde{B}(x'), j) & \text{if } i+j \neq 5\\ \operatorname{App}(\mathbb{A}^r \setminus \tilde{B}(x'), j) & \text{if } i+j = 5. \end{cases}$$
(6)

Let us consider the code D where App(C, j) is a "copy" of the code C in the layer A_j for j = 1, 2, 3. Notice that the layer A_4 contains no codewords of D.

Let again x = x'i where $x' \in \mathbb{A}^r$ and $i \in \mathbb{A}$. In what follows, we write in short I(x') = I(C; x') as usual, but in I(D; x) we always keep the D to distinguish between the two codes C and D. Due to (6) we have in the different layers j = 1, 2, 3, 4:

$$I(D; x'i) \cap A_j = \begin{cases} \emptyset & \text{if } j = 4, \\ \operatorname{App}(I(x'), j) & \text{if } j \neq 4 \text{ and } i + j \neq 5, \\ \operatorname{App}(C \setminus I(x'), j) & \text{if } j \neq 4 \text{ and } i + j = 5. \end{cases}$$
(7)

We use (1) and (2) to verify our claim that D gives an S-robust $\mathcal{SAM}_{\mathcal{A}^{r+1}}(1, m')$ with the given parameters S and m'. For that we also write $y \in \mathbb{A}^{r+1}$, $y \neq x$, as y = y'h where $y' \in \mathbb{A}^r$ and $h \in \mathbb{A}$.

First of all, we show (1), that is, $|I(D;x) \setminus I(D;y)| \ge S + 1$ for any distinct x and y. Denote $T = I(D;x) \setminus I(D;y)$. We calculate |T| examining three cases

depending on x = x'i and y = y'h. First the case where i = h, secondly, when x' = y', and finally the case that $x' \neq y'$ and $i \neq h$.

Case 1: Assume first that i = h, so both x and y are in the same layer A_i .

- (i) Let first i = 1. Notice that the layer A_4 contains no codewords of D. In the other three layers A_j , $j \neq 4$, we have $i + j \neq 5$ and thus in each of these layers we have the set $\operatorname{App}(I(x'), j) \setminus \operatorname{App}(I(y'), j)$ which contributes to T. This set contains the same codewords as $I(x') \setminus I(y')$ appended with j. Hence the cardinality of it equals $|I(x') \setminus I(y')|$. Consequently, we get $|T| = 3|I(x') \setminus I(y')|$.
- (ii) Assume then that i = 2 (the cases i = 3, 4 go similarly). Now the two layers A_j , j = 1, 2, both contribute $\operatorname{App}(I(x'), j) \setminus \operatorname{App}(I(y'), j)$ to T. The layer A_3 (since i + j = 2 + 3 = 5) contributes $\operatorname{App}(C \setminus I(x'), 3) \setminus \operatorname{App}(C \setminus I(y'), 3)$ to T. This equals the set $I(y') \setminus I(x')$ appended with 3. Hence $|T| = 2|I(x') \setminus I(y')| + |I(y') \setminus I(x')|$.

Case 2: Assume then that x' = y' (and thus $i \neq h$).

- (i) Let first i = 1. Assume that h = 2 (the cases h = 3, 4 go analogously and h cannot be 1). For the layers j = 1, 2 we have h + j ≠ 5 and i + j ≠ 5, so these layers contribute to T the sets App(I(x'), j)\App(I(y'), j). However, since x' = y' this set is the empty set. So neither layer contributes to T. In the layer A₃, since i + 3 ≠ 5 and h + 3 = 5, the layer 3 contributes App(I(x'), 3) \ App(C \ I(y'), 3) to T. The fact that y' = x' implies that this set equals I(x') appended with 3. Therefore, |T| = |I(x')|.
- (ii) Assume next that i = 2 (again i = 3, 4 are similar). Let first h = 1. The layer A_3 contributes $\operatorname{App}(C \setminus I(x'), 3) \setminus \operatorname{App}(I(y'), 3)$ which equals $\operatorname{App}(C \setminus I(x'), 3)$ since x' = y'. Other layers contribute nothing, so $|T| = |C \setminus I(x')|$. Assume then that h = 3 (the case h = 4 is similar and h cannot be 2). Now the layer A_2 (resp. A_3) contributes $\operatorname{App}(I(x'), 2) \setminus \operatorname{App}(C \setminus I(y'), 2)$ (resp. $\operatorname{App}(C \setminus I(x'), 3) \setminus \operatorname{App}(I(y'), 3)$). The layer A_1 contributes nothing, so $|T| = |I(x')| + |C \setminus I(x')| = |C|$.

Case 3: Assume next that both $x' \neq y'$ and $i \neq h$.

- (i) Let first i = 1. Suppose first that h = 2 (again the other cases h = 3, 4 are analogous). The layer A_1 (resp. A_2) contributes $I(x') \setminus I(y')$ appended with 1 (resp. 2) to T. The layer A_3 contributes $\operatorname{App}(I(x'), 3) \setminus \operatorname{App}(C \setminus I(y'), 3)$. This set equals $I(x') \cap I(y')$ appended with 3. Consequently, $|T| = 2|I(x') \setminus I(y')| + |I(x') \cap I(y')|$.
- (ii) Let then i = 2 (the cases i = 3, 4 go the same way). Assume first that h = 1. Again the layer A_1 (resp. A_2) contributes $I(x') \setminus I(y')$ appended with 1 (resp. 2) to T. The layer A_3 contributes $\operatorname{App}(C \setminus I(x'), 3) \setminus \operatorname{App}(I(y'), 3)$. This set equals $C \setminus (I(x') \cup I(y'))$ appended with 3. Therefore, $|T| = 2|I(x') \setminus I(y')| + |C| |I(x') \cup I(y')|$.

Suppose then that h = 3 (h = 4 is similar). Now the layer A_1 contributes $I(x') \setminus I(y')$ appended with 1. The layer A_2 contributes $\operatorname{App}(I(x'), 2) \setminus \operatorname{App}(C \setminus I(y'), 2)$ which corresponds to $I(x') \cap I(y')$. The layer A_3 contributes $\operatorname{App}(C \setminus I(x'), 3) \setminus \operatorname{App}(I(y'), 3)$ which corresponds to $C \setminus (I(x') \cup I(y'), 3)$

 $I(y')). \text{ This implies that } |T| = |I(x') \setminus I(y')| + |I(x') \cap I(y')| + |C| - |I(x') \cup I(y')| = |I(x')| + |C| - |I(x') \cup I(y')|.$

It is now straightforward to check that each of these values of |T| is bounded from below by min $\{2(s+1), i_{min}, |C| - i_{max}\}$. The claim for S follows from (1).

We can get the parameter m' using (2) and the previous calculations. For (2) we need (besides S above) the cardinality of the intersections $I(D; x) \cap I(D; y)$, $x \neq y$. Since for any sets X and Y, we have $X \cap Y = X \setminus (X \setminus Y)$, we obtain the value $|I(D; x) \cap I(D; y)|$ using T (which corresponds to $X \setminus Y$) and the set I(D; x) (corresponding to X), which is given in (7).

If x = x'1 and y = y'1, then the three layers A_j , j = 1, 2, 3 contribute App(I(x'), j) to I(D; x). Consequently, |I(D; x)| = 3|I(x)| and the intersection $|I(D; x) \cap I(D, y)| = |I(D; x)| - |T| = 3|I(x')| - 3|I(x') \setminus I(y')| = 3|I(x') \cap I(y')|$ where |T| comes from Case 1(i) above. The other cases are similar and we only give the results:

The size of the intersection $|(D; x) \cap I(D; y)|$ belongs to the set $\{3|I(x') \cap I(y')|, 2|I(x') \cap I(y')| + |C| - |I(x') \cup I(y')|, 2|I(x')|, |I(x')|, |I(x') \cap I(y')| + |I(x')|, |I(x') \cap I(y')| + |I(y')|, |I(x') \cup I(y')|\}$. It is easy to check that all of these values are bounded from above by $\max\{3(m-2s-1), 2i_{max}, 2(m-2s-1) + |C| - l\}$. This yields the claim for m'.

5 Line graphs

In this section, we consider the problem of robust associative memories in the line graphs. Assuming G = (V, E) is a graph, the line graph L(G) of G is defined as follows. The vertex set of L(G) consists of the edges of G, and two vertices in L(G) are adjacent if the corresponding edges are adjacent in G, i.e., they share a common vertex. Due to the definition of line graphs, studying associative memories in L(G) is equivalent to considering analogous problems in the original graph G for the edges. Hence, we propose the following definitions for the edges of G. For an edge $e \in E$, the notation B(e) is used for the set of edges associated to e, i.e., adjacent to e (also including e itself). Assuming $C \subseteq E$ is code, we define $I(e) = B(e) \cap C$. Notice that in the case of edges we only consider t-association with t = 1 implying the similar restriction for the line graphs. Therefore, for the rest of the section, let t = 1.

Let s be a nonnegative integer. Recall that we had the earlier condition (1) for distinct vertices $x, y \in V$. In the case of *edges*, assuming $C \subseteq E$, this is equivalent to stating that

$$|I(C;e_1) \setminus I(C;e_2)| \ge s+1 \tag{8}$$

for any distinct edges $e_1, e_2 \in E$. In the following theorem, we give a characterization of the graphs admitting a code meeting the previous condition.

Theorem 10. Let G be a simple connected graph on at least three vertices. The graph G admits a code satisfying the condition (8) if and only if $\delta(G) \ge s + 2$ and for any 3-cycle C_3 in G each vertex u belonging to C_3 has $\deg(u) \ge s + 3$.

Proof. Let G = (V, E) be a graph. Notice first that if a code $C \subseteq E$ satisfies the condition (8), then any C' such that $C \subseteq C'$ also meets the condition.

Therefore, the graph G admits such a code if and only if the code C = E satisfies the condition. Hence, for the graph G, it suffices to verify that

$$|B(e_1) \setminus B(e_2)| \ge s + 1$$

for any distinct $e_1, e_2 \in E$.

Assume first that G admits a code satisfying the condition (8). Assume to the contrary that $\delta(G) \leq s + 1$, or there exists a 3-cycle \mathcal{C}_3 and a vertex $u \in \mathcal{C}_3$ such that $\deg(u) \leq s + 2$. Clearly, $\delta(G) \geq 1$. If there exists a vertex $u \in V$ such that $\deg(u) \leq s + 1$, then consider an edge $e_1 = uv$ incident with u. Let us first observe that the vertex v cannot have $\deg(v) = 1$. Indeed, in that case there would be an edge e' = uz, $e_1 \neq e'$, due to the fact that Gis connected on at least three vertices. This would yield $|B(e_1) \setminus B(e')| = 0$, contradicting (8). Hence $\deg(v) \geq 2$, so we can choose an edge $e_2 = vw$ distinct from uv. Then, if $\deg(u) \leq s+1$, we obtain a contradiction as $|B(e_1) \setminus B(e_2)| \leq$ s. Assume then that there exist a 3-cycle \mathcal{C}_3 and a vertex u in it such that $\deg(u) \leq s+2$. Let then $e_1 = uv$ and $e_2 = uw$ be distinct edges of \mathcal{C}_3 . This again implies a contradiction since $e_3 = vw$ belongs to E as part of the 3-cycle and $|B(e_1) \setminus B(e_3)| \leq s$.

Assume then that $\delta(G) \geq s + 2$ and for any 3-cycle \mathcal{C}_3 in G each vertex u belonging to \mathcal{C}_3 has deg $(u) \geq s+3$. Let $e_1 = uv$ and e_2 be distinct edges in G. If e_1 and e_2 are not adjacent to each other, then we obtain (using the assumption) that

$$|B(e_1) \setminus B(e_2)| \ge 2(s+1) + 1 - 2 = 2s + 1$$

and we are done. Hence, we may assume that e_2 is adjacent to e_1 and denote $e_2 = vw$. Assume first that there is no edge between u and w. This implies that $|B(e_1) \setminus B(e_2)| \ge s + 2 - 1 = s + 1$ and we are done. Therefore, we may assume that $e_3 = uw \in E$. Thus e_1 , e_2 and e_3 form a 3-cycle. By the assumption, we now have $\deg(u) \ge s + 3$. Thus, we obtain that (the graph G is simple)

$$|B(e_1) \setminus B(e_2)| \ge s + 3 - 2 = s + 1$$

and the claim follows.

In the following theorem, we give a characterization for the codes satisfying the condition (8).

Theorem 11. Let G = (V, E) be a simple connected graph on at least three vertices admitting a code satisfying the condition (8). Then a code $C \subseteq E$ satisfies the condition (8) if and only if

- (a) each vertex of G is incident with at least s + 2 edges of C and
- (b) for any 3-cycle C_3 in G each vertex of C_3 is incident with at least s + 1 edges of C not belonging to C_3

Proof. Assume first that $C \subseteq E$ is a code satisfying the condition (8). Assume to the contrary that the condition (a) is not satisfied, i.e., there exists a vertex $u \in V$ such that u is incident with at most s + 1 edges of C. Let $e_1 = uv$ be any edge of C incident with u. Then, for any distinct edge $e_2 = vw$ (not necessarily in C), we have

$$|I(C;e_1) \setminus I(C;e_2)| \le s$$

and a contradiction follows. Assume then to the contrary that the condition (b) is not satisfied, i.e., there exists a 3-cycle C_3 and a vertex $u \in C_3$ such that u is incident with at most s edges of C not belonging C_3 . As the condition (a) is satisfied, there exists distinct edges $e_1 = uv \in C$ and $e_2 = uw \in C$ such that e_1 and e_2 are part of the 3-cycle C_3 . Hence, considering the edge $e_3 = vw \in E$, we obtain a contradiction as

$$|I(C;e_1) \setminus I(C;e_3)| \le s.$$

Assume then that the conditions (a) and (b) hold. Now reasoning similarly as in the proof of Theorem 10, we obtain that (8) is satisfied.

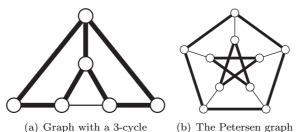


Figure 4: The code consists of the bold edges.

In Figure 4(a), there is an example of a graph with 3-cycle. Let the code C consist of the bold edges in the figure. Clearly, C satisfies the conditions (a) and (b) of Theorem 11 for s = 0.

Recall that a reference set $C \subseteq E$ satisfying the condition (8) or the conditions of the previous theorem gives an *s*-robust $SAM_G(1,m)$ (regarding the edge set of *G*) with

$$m = \max_{e_1 \neq e_2} \{ |I(C; e_1) \cap I(C; e_2)| \} + 2s + 1.$$

In order to construct such reference sets, we introduce the concept of k-factors, where k is a positive integers. We say that a subgraph H of G is k-factor if H contains all the vertices of G and is k-regular. For an extensive coverage on k-factors, we refer the interested reader to the survey [13]. Now we are ready to present the following corollary of Theorem 11.

Corollary 12. If G = (V, E) is a graph without 3-cycles, then the edges of any (s + 2)-factor form a reference set $C \subseteq E$ giving an s-robust $SAM_G(1,m)$ (regarding the edge set of G) with m = 3s + 3 and no reference set implying smaller m exists.

An example of this corollary for s = 0 is the 2-factor (denoted by the bold edges) in the Petersen graph of Figure 4(b).

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